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Ukupan broj zapisa na URL-u: 2

Broj izvezenih zapisa: 2

Naslov	URL	Autori	Naslov izvornika
Complete coverage of large seabed areas using sonar data-based path planning for an autonomous marine vehicle		Kapetanović, Nadir	
Guidance and control of autonomous underwater agents with acoustically aided navigation		Nađ, Đula	