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Naslov	URL	Autori	Naslov izvornika
State estimation and multiple moving object tracking on Riemannian manifolds		Bičanić, Borna	
Robust visual place recognition using deep representations and sequence-based image matching		Maltar, Jurica	
Human action and motion prediction in industrial human-robot shared environments using probabilistic decision-making methods		Petković, Tomislav	
Autonomous agent localization in dynamic scenarios based on visual sensor data fusion		Popović, Goran	
High-dimensional trajectory optimization for robot motion planning based on Gaussian processes		Petrović, Luka	
Združeno prognoziranje značajki i njihova pomaka za predviđanje semantičke budućnosti u videu		Šarić, Josip	
Moving objects detection and tracking by omnidirectional sensors of a mobile robot		Marković, Ivan	