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Broj izvezenih zapisa: 7

Naslov	URL	Autori	Naslov izvornika
Complete coverage of large seabed areas using sonar data-based path planning for an autonomous marine vehicle		Kapetanović, Nadir	
A hyper-heuristic approach to achieving long-term autonomy in a heterogeneous swarm of marine robots		Babić, Anja	
Human action and motion prediction in industrial human-robot shared environments using probabilistic decision-making methods		Petković, Tomislav	
Control of autonomous surface marine vessels for underwater vehicle localization using single range acoustic measurements		Mandić, Filip	
Guidance and control of autonomous underwater agents with acoustically aided navigation		Nađ, Đula	
Primjena adaptivnih neizrazitih algoritama u turbinskoj regulaciji hidroelektrana		Mišković, Ivan	
Primjena vlastitih oscilacija u vođenju i upravljanju plovilima		Mišković, Nikola	