

Time of export: 28.03.2024. 13:52:20

Repository: dr.nsk.hr

Number of records on this URL: 7

Records exported: 7

Title	URL	Authors	Host item title
State estimation and multiple moving object tracking on Riemannian manifolds		Bićanić, Borna	
Robust visual place recognition using deep representations and sequence-based image matching		Maltar, Jurica	
Human action and motion prediction in industrial human-robot shared environments using probabilistic decision-making methods		Petković, Tomislav	
Autonomous agent localization in dynamic scenarios based on visual sensor data fusion		Popović, Goran	
High-dimensional trajectory optimization for robot motion planning based on Gaussian processes		Petrović, Luka	
Združeno prognoziranje značajki i njihova pomaka za predviđanje semantičke budućnosti u videu		Šarić, Josip	
Moving objects detection and tracking by omnidirectional sensors of a mobile robot		Marković, Ivan	