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Title	URL	Authors	Host item title
Artificial intelligence-based methods for interaction force estimation and mediated navigation of a robot manipulator on a mobile base		Kružić, Stanko	
Detekcija ljudi na slikama iz zraka upotrebom višemodelnog pristupa dubokog učenja		Kundid Vasić, Mirela	
Model poučavanja agentske paradigme korištenjem simulacijskih okruženja		Rakić, Krešimir	