

<https://dr.nsk.hr/user/profile/mbz/315241>

Vrijeme izvoza: 26.09.2024. 17:38:54

Repozitorij: dr.nsk.hr

Ukupan broj zapisa na URL-u: 7

Broj izvezenih zapisa: 7

<b>Naslov</b>	<b>URL</b>	<b>Autori</b>	<b>Naslov izvornika</b>
State estimation and multiple moving object tracking on Riemannian manifolds		Bićanić, Borna	
Robust visual place recognition using deep representations and sequence-based image matching		Maltar, Jurica	
Human action and motion prediction in industrial human-robot shared environments using probabilistic decision-making methods		Petković, Tomislav	
Autonomous agent localization in dynamic scenarios based on visual sensor data fusion		Popović, Goran	
High-dimensional trajectory optimization for robot motion planning based on Gaussian processes		Petrović, Luka	
Združeno prognoziranje značajki i njihova pomaka za predviđanje semantičke budućnosti u videu		Šarić, Josip	
Moving objects detection and tracking by omnidirectional sensors of a mobile robot		Marković, Ivan	